

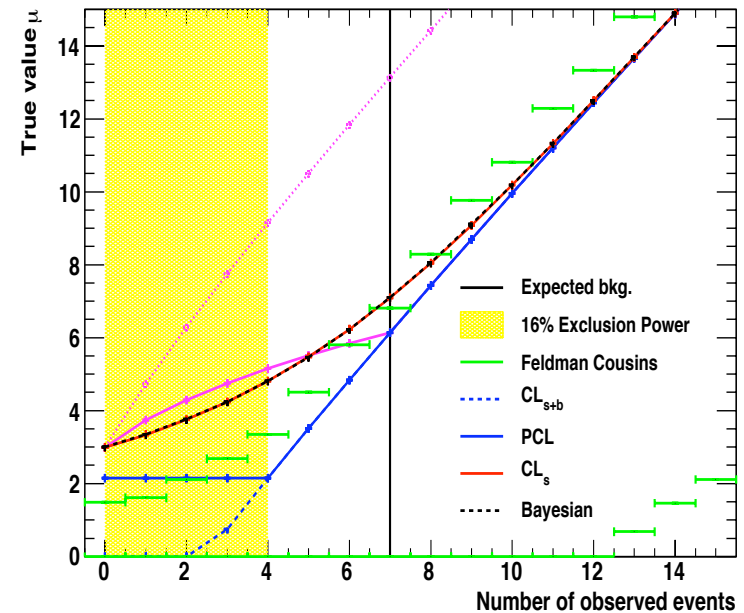
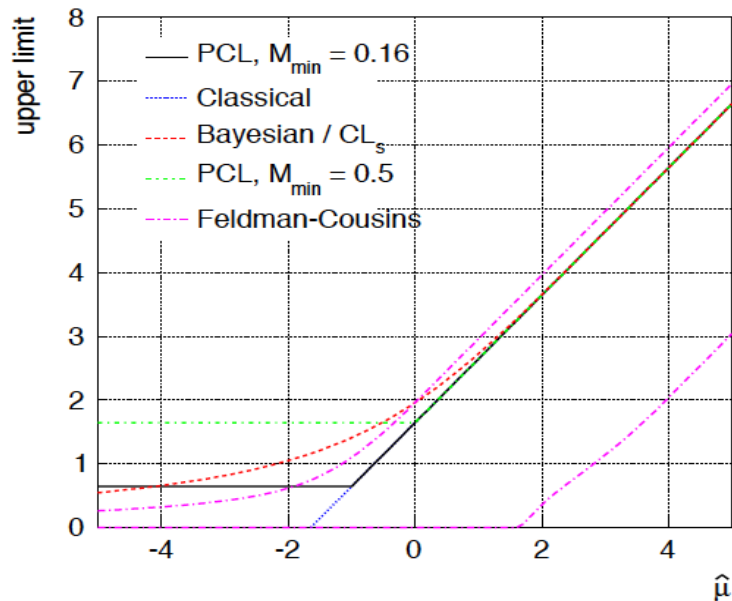
Confidence Intervals and Limits for Pedestrians



Markus Schumacher



GK Lecture, Freiburg, 26 - 28 September 2017



Goal of the lecture: understand the content and interpretation of the two figures

Outline

Lecture 1: Basics (26.9.)

- Motivation
- Frequentist and Bayesian Probability
- Parameter Estimation from Maximum Likelihood
- Frequentist Confidence Intervals a la Neyman and Coverage
- Bayesian Credibility Interval from Likelihood Principle

Lecture 2: Limits for Gaussian Probability Distribution (27.9)

- Connection of Frequentist Limit to Frequentist Hypothesis Test
- Limits close to physical boundary
- Frequentist and Bayesian Limits
- Modified Frequentist: CL_s Method and Power Constrained Limit (PCL)
- Unified Approach, Feldman- Cousins Intervals (FCL)

Lecture 3: Limits for Poisson Distribution (28.9.)

- Confidence Intervals
- Limits close to physical boundary
- Frequentist, Bayesian, PCL, CL_s, FC Limits

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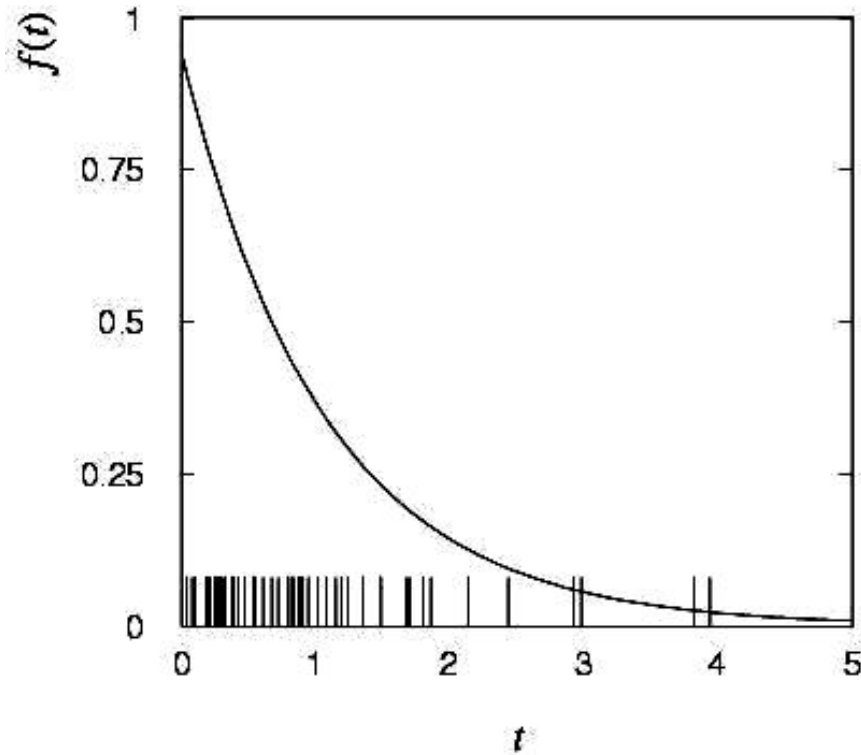
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Motivation

Consider measurement of 50 decay times t of instabile particle ($\tau_{\text{true}} = 1$)
Random variable (RV) t follows exponetial PDF. $f(t; \tau) = \frac{1}{\tau} e^{-t/\tau}$



Goal 1: estimate of life time

$$\hat{\tau} = 1.062$$

and estimate for dispersion of estimate
in repeated identical experiments
→ variance and standard deviation

$$\widehat{V}[\hat{\tau}] = \frac{\hat{\tau}^2}{n} \quad \hat{\sigma}_{\hat{\tau}} = 0.151$$

Goal 2: try to make a probabilistic statement connecting
measured value and true value
→ confidence interval $[a,b]$ and/or limit c_{95}

Motivation (2)

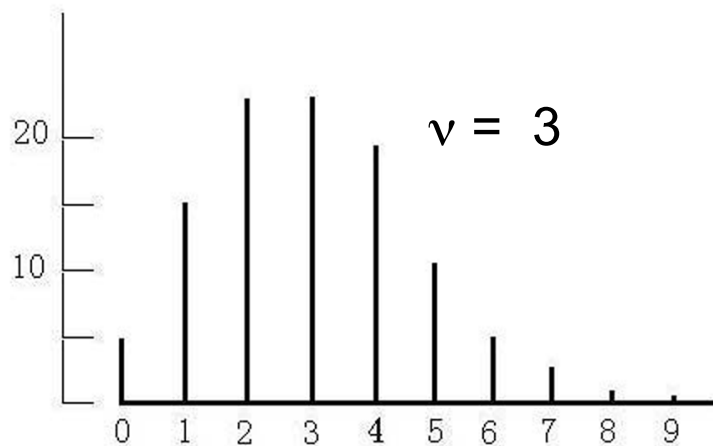
Consider measurement of a counting rate $n_{obs}=4$ ($n_{true} = \nu = 3$)
Random variable (RV) n follows Poisson PDF.

$$f(n; \nu) = \frac{\nu^n}{n!} e^{-\nu} \quad (n \geq 0) \quad E[n] = V[n] = \nu$$

Goal 1: estimate for ν : $\hat{\nu}$

$$\hat{\nu} = n_{obs} = 4$$

estimate of variance $\hat{V}[\hat{\nu}] = \hat{\nu} = 4$
and
of standard deviation $\hat{\sigma}[\hat{\nu}] = \sqrt{\hat{\nu}} = 2$



Naive estimate of confidence interval to CL = 68%

$$\text{naive CI} = [n_{obs} - \sigma, n_{obs} + \sigma] = [2, 0; 6, 0] \quad \text{length} = 4, 0$$

$$\text{correct frequentist CI} = [2, 1; 7, 2] \quad \text{length} = 5, 1$$

→ estimate ± 1 -sigma only correct if estimate follows Gauss PDF

Motivation (3)

First step in interpretation:

Estimate of parameter and its variance (often with ML method)

Second step: estimate of

- a two-sided confidence interval $[a,b]$ at 68% confidence level CL
- or single-sided confidence interval = limit c_{95} at 95% CL

which make a statistical statement between outcome of experiment and the true value of a parameter

Two statistical schools: Frequentist and Bayesian statistics

- different method for construction of confidence interval
- numerical identical for sample size $n_{sp} \rightarrow \infty$ and estimated value not close to physical boundary
(e.g. estimates $m_v^2 = -5 \pm 2 \text{ eV}^2$ $s = n-b = 0-3 = -3$)
- interpretation always different

Modified (pseudo)-frequentist methods:

Power Constrained Limit (PCL), CL_s Limit, Feldman-Cousins Limit (FCL)

Axiomatic Definition of Probability

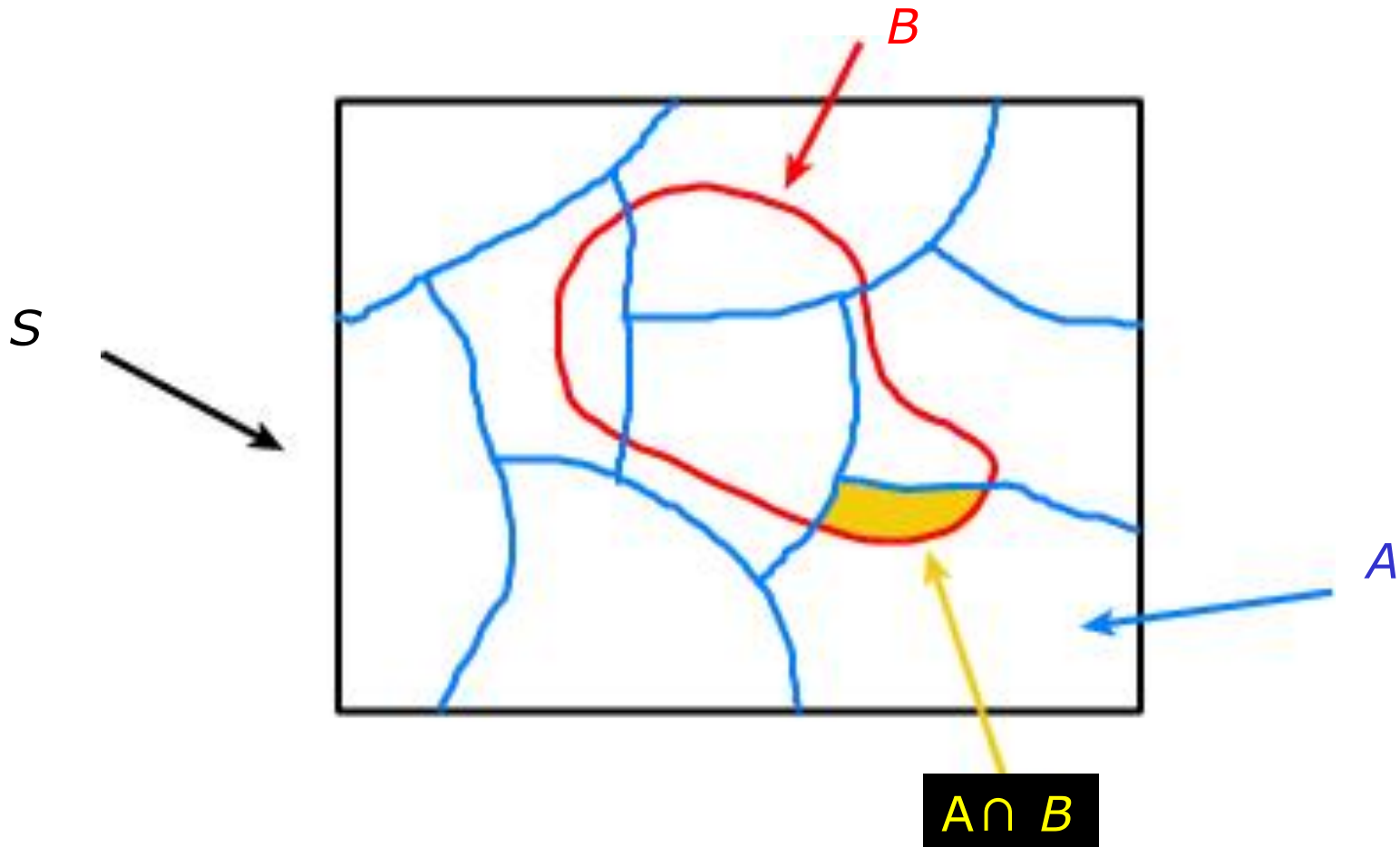
For all $A \subset S$, $P(A) \geq 0$

$P(S) = 1$

Kolmogorov
Axioms (1933)

If $A \cap B = \emptyset$, $P(A \cup B) = P(A) + P(B)$

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$



Axiomatic Definition of Probability

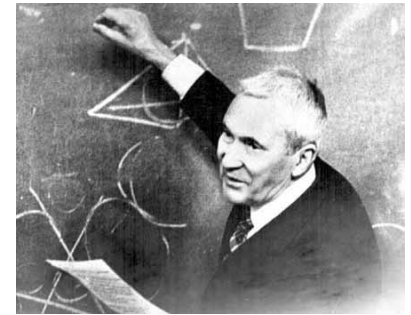
Consider set S with subsets A, B, \dots

Assign to each set a number between 0 and 1 with

For all $A \subset S, P(A) \geq 0$

$$P(S) = 1$$

If $A \cap B = \emptyset, P(A \cup B) = P(A) + P(B)$



Kolmogorov
Axioms (1933)

Conditional probability (for $P(B) \neq 0$)

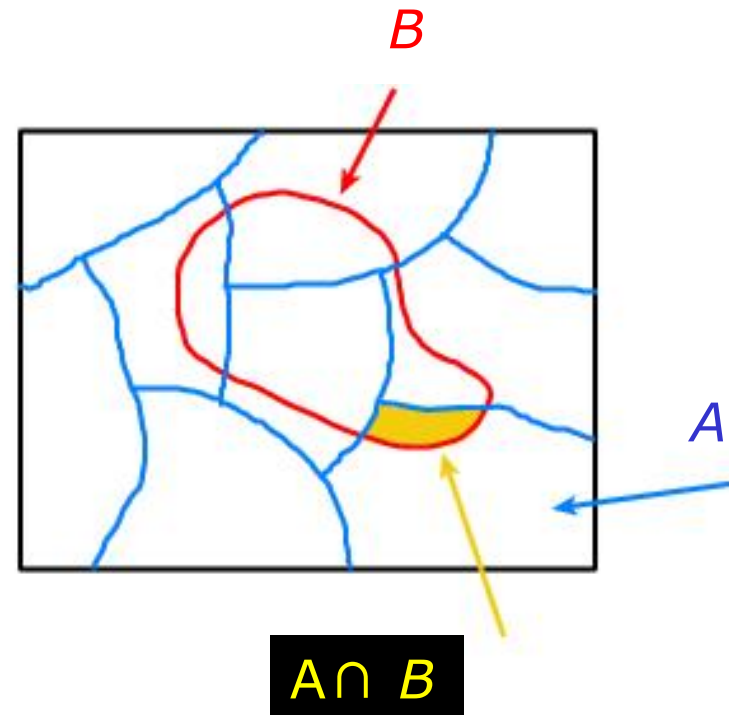
$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

If subsets A, B independent:

$$P(A \cap B) = P(A)P(B)$$

$$P(A|B) = \frac{P(A)P(B)}{P(B)} = P(A)$$

S



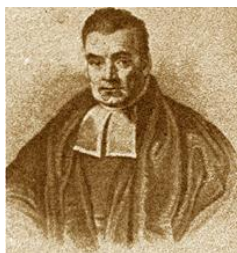
Axiomatic Definition of Probability (2)

From the definition of conditional probability:

$$P(A|B) = \frac{P(A \cap B)}{P(B)} \quad P(A \cap B) = P(B \cap A) \quad P(B|A) = \frac{P(B \cap A)}{P(A)}$$

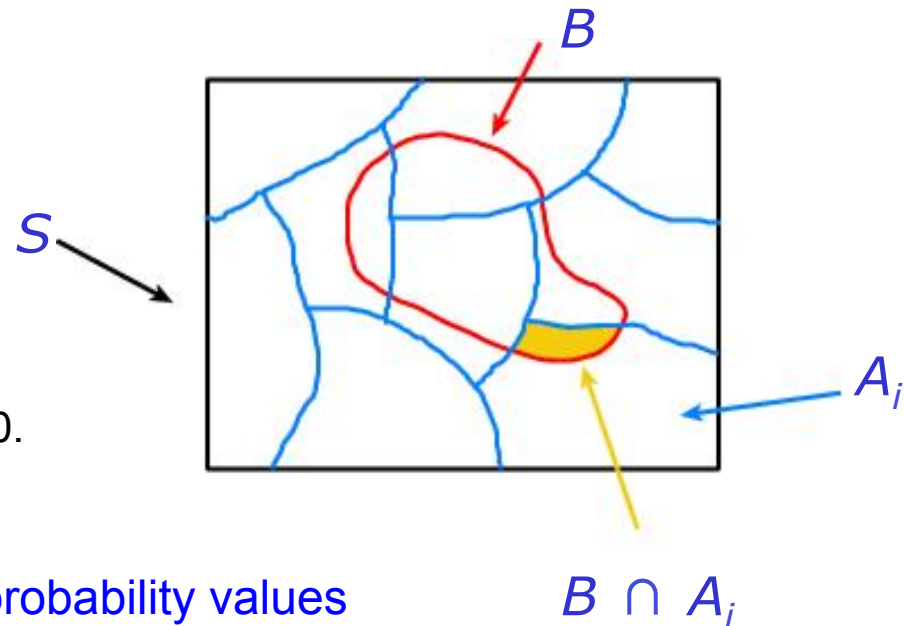
$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$

$$P(B) = \sum_i P(B|A_i)P(A_i)$$



Thomas Bayes (1702–1761)

An essay towards solving a problem in the doctrine of chances,
Philos. Trans. R. Soc. **53** (1763) 370.



Axiomatic definition not helpful in real life.

Need: definition of subsets, rule to assign probability values

2 Schools: Frequentists and Bayesians

Bayes Theorems holds and is accepted in both schools

Controversy about: what are the subsets, to which probability values can be assigned

Frequentist

and

Bayesian

Subsets:

Outcome of (repeatable) experiment

Any hypothesis

Assignment of probabilities:

Relative frequency in limit nr of trials \rightarrow inf.

Degree of belief in hypothesis

$$P(A) = \lim_{n \rightarrow \infty} \frac{\text{times outcome is in } A}{n}$$

$P(A)$ = degree of belief that A is true

P (SUSY exists)

$P(9.81 \text{ m/s}^2 < g < 9.82 \text{ m/s}^2)$

$P(\text{rain in Freiburg on 27.9.2017})$

Not defined. Either 0 or 1.

No problem. This is the goal.

Bayesian definition: More general (includes Frequentist definition)

Applicable to singular events, “true” values, ...

Does not care about repeatability of experiment

Needs a-priori probability in application of Bayes theorem

Bayesian Statistics: General Philosophy

How to use Bayes theorem to update “degree of belief” in light of data

Probability to observe data assuming a hypothesis H (true value of a parameter)
Likelihood function (also used by Frequentists)

$$P(H|\vec{x}) = \frac{P(\vec{x}|H)\pi(H)}{\int P(\vec{x}|H)\pi(H) dH}$$

A-priori probability,
i.e. before data taking
(not defined in Frequentist school)

Posterior probability, i.e.
after analysis of the data
(not defined in Frequentist school)

Normalisation includes sum/integral
over all possible hypothesis/par. values

No general rule for choice of a-priori probability → “subjective”

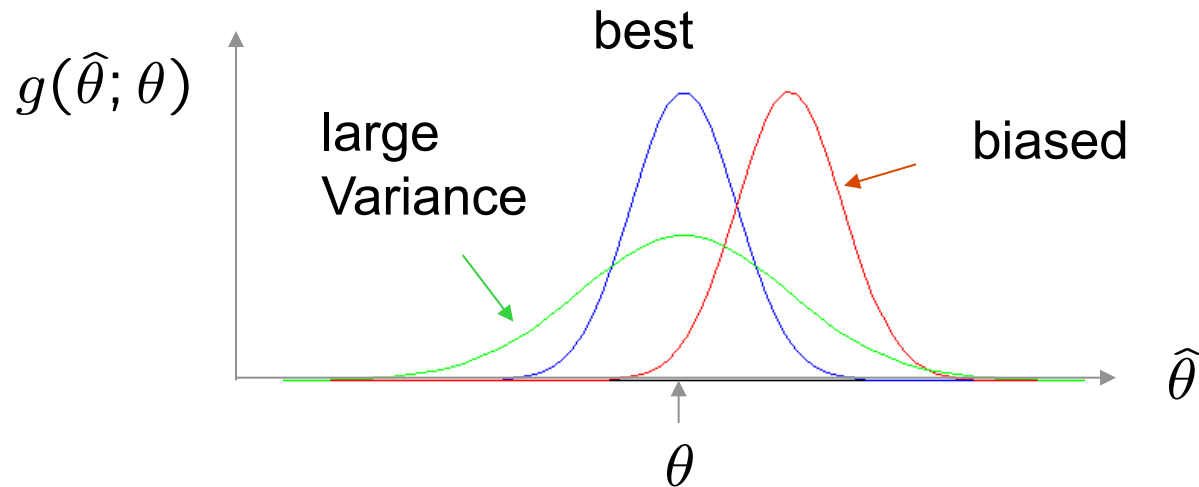
“Objective” prior = uniform? - not well defined probability for infinite parameter space
- uniform in θ , θ^2 , $\sqrt{\theta}$, $\ln \theta$, ... ?

→ Jeffrey Prior $p(\theta) = \sqrt{\text{Information}(\theta)}$
uniform for mean μ of Gauss pdf
 $1/\sqrt{\mu}$ for Poisson $1/\tau$ for $\exp(-t/\tau)$

Properties of estimators

Estimator is a function of the sample to determine an unknown parameter

Estimator is a randomvariable and hence has a PDF $g(\hat{\theta}; \theta)$



We want small (or vanishing) Bias (systematic error) $b = E[\hat{\theta}] - \theta$

→ expectation value from repeated measurment should be = true value

We want small variance (statistical uncertainty): $V[\hat{\theta}]$

→ small bias and small variance are in general competing criteria

Minimum Variance Bound

In information theory one can show, that there is a lower limit for the variance for the estimator of a parameter (if the sample range is independent on the true parameter value)

Minimum Variance Bound (MVB) from Rao-Cramer-Frechet-Inequality

$$V[\hat{\theta}] \geq \frac{\left(1 + \frac{\partial b}{\partial \theta}\right)^2}{E\left[-\frac{\partial^2 \log \mathcal{L}}{\partial \theta^2}\right]}.$$

$$V[\hat{\theta}] \geq \frac{\left(1 + \frac{\partial b}{\partial \theta}\right)^2}{E\left[\left(\frac{\partial \log \mathcal{L}}{\partial \theta}\right)^2\right]}.$$

Information according to R.A Fisher: $I(\theta) \equiv E\left[\left(\frac{\partial \log \mathcal{L}}{\partial \theta}\right)^2\right] = E\left[-\frac{\partial^2 \log \mathcal{L}}{\partial \theta^2}\right]$

→ the larger the information, the smaller the statistical uncertainty

Likelihood and Desired Properties of Estimators

Given a sample of measurements $(x_1..x_n)$ for a RV x following PDF $f(x;\theta)$
the common PDF for the sample is given by:

$$f(x_1, \dots, x_n; \theta) = \prod_{i=1}^n f(x_i; \theta)$$

Considering the samples fixed,
this is called the likelihood:

$$L(\vec{\theta}) = \prod_{i=1}^n f(x_i; \vec{\theta})$$

Consistency

$$\hat{\theta}^{(n)} \xrightarrow{n \rightarrow \infty} \theta$$

Bias

$$b^{(n)} = E[\hat{\theta}^{(n)}] - \theta$$

bias should be small / „0“
b=0 estimator unbiased

consistent estimators with finite variance
are asymptotically $(n \rightarrow \infty)$ unbiased

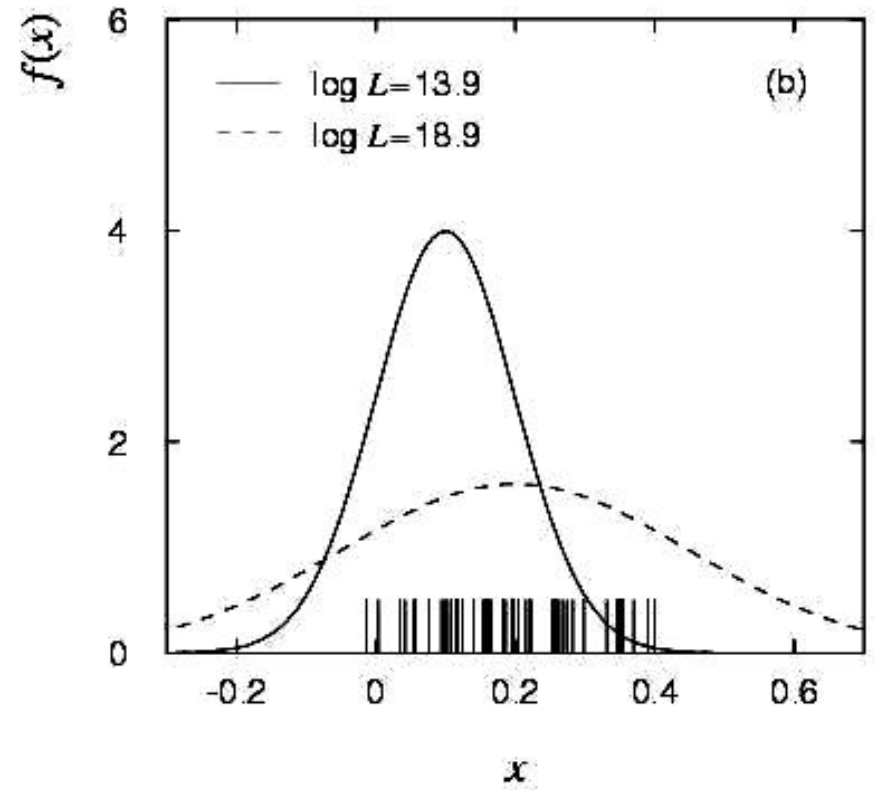
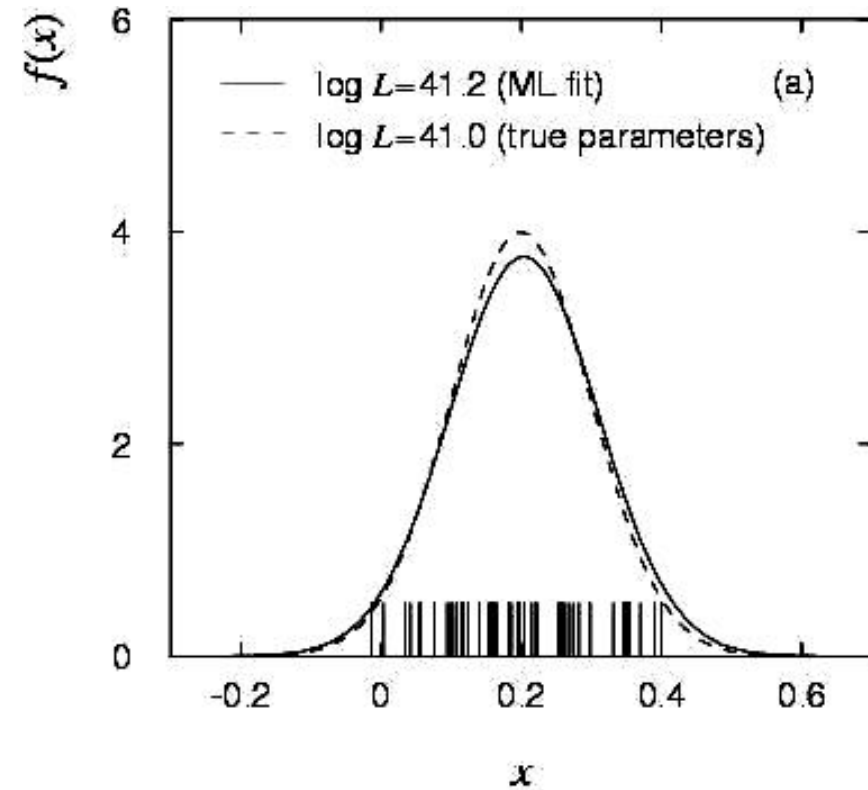
Efficiency

$$\text{Effizienz} [\hat{\theta}^{(n)}] = \frac{SMV}{V [\hat{\theta}^{(n)}]}$$

Efficiency should
be close to „1“

Maximum-Likelihood: Basic Idea

If hypothetically value θ close to true value θ_{true} ,
then probability to observe actual measured sample to is large



Hence define “Maximum Likelihood (ML)” estimator as parameter value, which maximises likelihood den Parameterwert

$$\mathcal{L}(\hat{\theta}) = \prod_{i=1}^n f(x_i; \hat{\theta}) = \text{Maximum.}$$

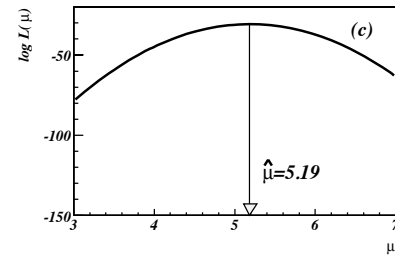
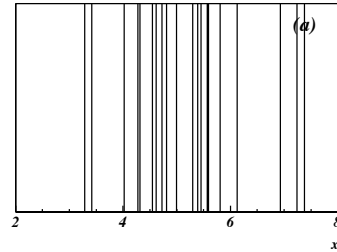
$$\left. \frac{\partial \log \mathcal{L}}{\partial \theta} \right|_{\hat{\theta}} = 0$$

Estimator for Mean Value of Gauss-PDF

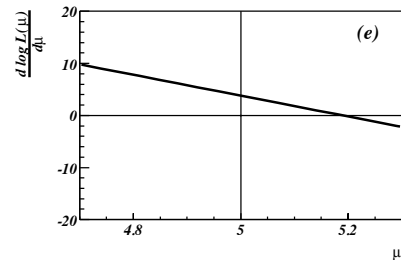
Gauss-PDF

$\mu=5, \sigma=1$

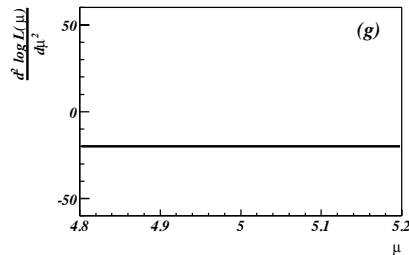
sample size $N=20$



$$\hat{\mu} \approx 5.19$$



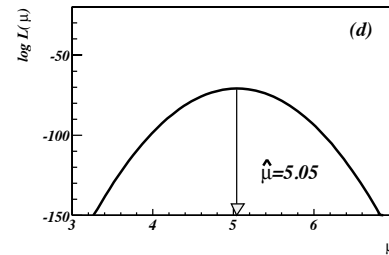
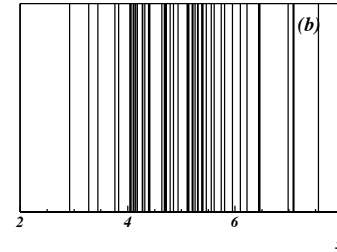
$$I(\mu) = 20$$



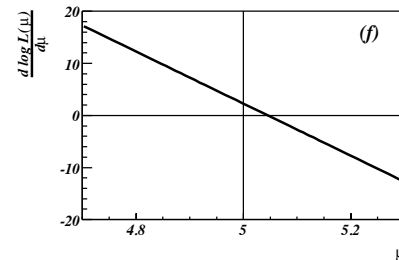
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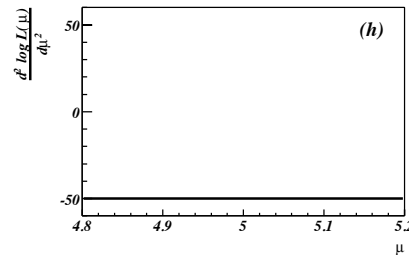
sample size $N=50$



$$\hat{\mu} \approx 5.05$$



$$I(\mu) = 50$$



Estimator for Mean of Exponential PDF

Consider Exponential PDF: $f(t; \tau) = \frac{1}{\tau} e^{-t/\tau}$

and sample of n independent measurements t_1, \dots, t_n

The likelihood is given by $L(\tau) = \prod_{i=1}^n \frac{1}{\tau} e^{-t_i/\tau}$

The value of τ which maximises $L(\tau)$, also yields the maximum of its logarithm (the log/ln-likelihood function):

$$\ln L(\tau) = \sum_{i=1}^n \ln f(t_i; \tau) = \sum_{i=1}^n \left(\ln \frac{1}{\tau} - \frac{t_i}{\tau} \right)$$

Estimator for Mean of Exponential PDF (2)

$$\log \mathcal{L}(\tau) = \sum_{i=1}^n \log f(t_i; \tau) = \sum_{i=1}^n \left(\log \frac{1}{\tau} - \frac{t_i}{\tau} \right) = n \log \frac{1}{\tau} - \frac{1}{\tau} \sum_{i=1}^n t_i$$

Determination of maximum

$$0 = \left. \frac{\partial \log \mathcal{L}(\tau)}{\partial \tau} \right|_{\tau=\hat{\tau}} = -n \frac{1}{\hat{\tau}} + \frac{1}{\hat{\tau}^2} \sum_{i=1}^n t_i$$

Yields the ML estimator:

$$\hat{\tau} = \frac{1}{n} \sum_{i=1}^n t_i$$

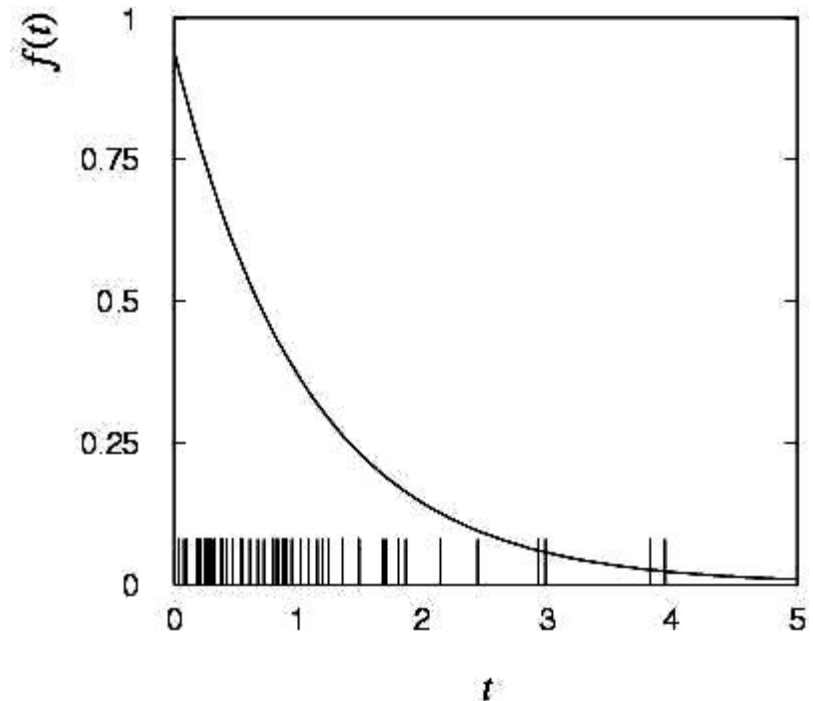
which is the arithmetic mean of the sample and hence consistent and unbiased

Monte Carlo Test:

Generate 50 Measurements for $\tau = 1$.

The ML estimator yields:

$$\hat{\tau} = 1.062$$



Estimator for Mean of Exponential PDF (3)

Variance of sample mean is given by: $V[\hat{\tau}] = \frac{1}{n} V[t] = \frac{1}{n} \tau^2$

Comparison with Minimum Variance Bound (MVB) :

$$\frac{\partial^2 \log \mathcal{L}}{\partial \tau^2} = \frac{n}{\tau^2} \left(1 - \frac{2}{n\tau} \sum_{i=1}^n t_i \right) = \frac{n}{\tau^2} \left(1 - \frac{2\hat{\tau}}{\tau} \right)$$

$$V[\hat{\tau}] \geq \frac{-1}{E \left[\frac{n}{\tau^2} \left(1 - \frac{2\hat{\tau}}{\tau} \right) \right]} = \frac{-1}{\frac{n}{\tau^2} \left(1 - \frac{2E[\hat{\tau}]}{\tau} \right)} = \frac{\tau^2}{n}$$

Hence ML Estimator is efficient for this problem

Estimator for Variance

$$\widehat{V[\hat{\tau}]} = \frac{\hat{\tau}^2}{n}$$

Maximum-Likelihood: Estimate of Variance

Graphically $\Delta \ln L = 0,5$

$$[1.02 - 0.12, 1.02 + 0.16]$$

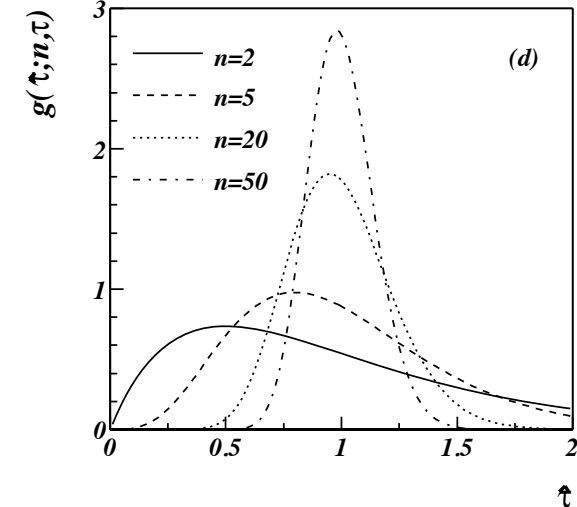
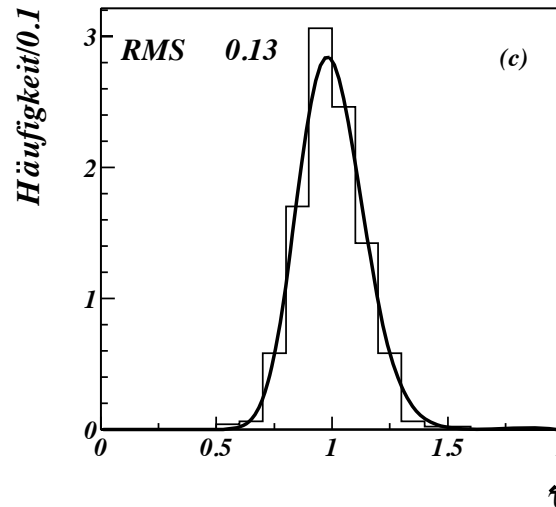
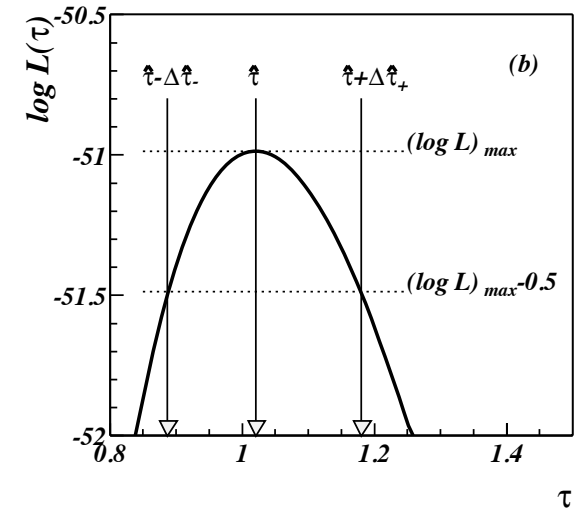
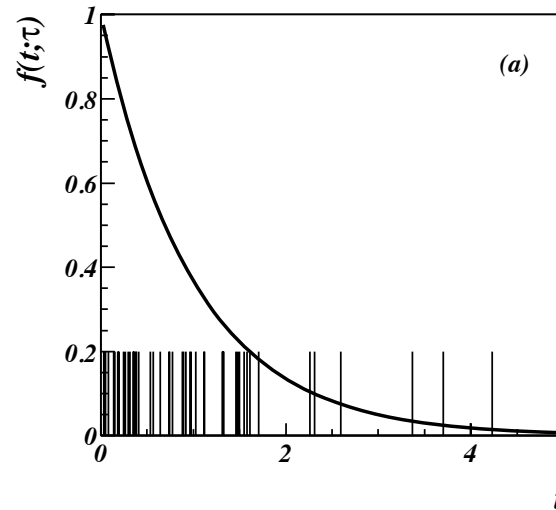
Analytically or
curvature in minimum

$$\widehat{V}[\hat{\tau}] = \frac{\hat{\tau}^2}{n} \approx 0.021$$

$$\hat{\sigma} \approx 0.14$$

MC-Method:

0.13,



Estimator for Mean and Variance of Gauss PDF

Consider n independent measurements x_1, \dots, x_n , from Gauss PDF $f(x; \mu, \sigma^2)$

$$f(x; \mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-(x-\mu)^2/2\sigma^2}$$

The Log-Likelihood Function is given by:

$$\begin{aligned} \ln L(\mu, \sigma^2) &= \sum_{i=1}^n \ln f(x_i; \mu, \sigma^2) \\ &= \sum_{i=1}^n \left(\ln \frac{1}{\sqrt{2\pi}} + \frac{1}{2} \ln \frac{1}{\sigma^2} - \frac{(x_i - \mu)^2}{2\sigma^2} \right) . \end{aligned}$$

Set derivatives w.r.t. μ, σ^2 to zero, and solve equations

$$0 = \left. \frac{\partial \log \mathcal{L}(\mu, \sigma^2)}{\partial \mu} \right|_{\mu=\hat{\mu}} = \sum_{i=1}^n \frac{(x_i - \hat{\mu})}{\sigma^2} \qquad 0 = \left. \frac{\partial \log \mathcal{L}(\mu, \sigma^2)}{\partial \sigma^2} \right|_{\sigma^2=\hat{\sigma}^2}$$

Estimator for Mean and Variance of Gauss PDF (2)

Yields the maximum likelihood estimators:

$$\hat{\mu} = \frac{1}{n} \sum_{i=1}^n x_i , \quad \hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \hat{\mu})^2 .$$

Arithmetic mean is estimator for μ , hence consistent and unbiased

But estimator for variance σ^2 is biased $E[\hat{\sigma}^2] = \frac{n-1}{n} \sigma^2 ,$

only asymptotically unbiased: $b \rightarrow 0$ für $n \rightarrow \infty$.

Reminder:
is unbiased estimator for variance

$$s^2 = \frac{1}{n-1} \sum_{i=1}^n (x_i - \hat{\mu})^2$$

Properties of ML Estimators

Consistency: if expectation value and variance of estimator finite and sample space independent of parameter

Bias: No general statement possible. Investigate with MC method
Asymptotically ($n \rightarrow \infty$) unbiased if consistent.

Efficiency: If an efficient estimator exists it is given by ML method (if sample range independent of parameter)
Efficiency $\rightarrow 1$ for $n \rightarrow \infty$.

Asymptotically ($n \rightarrow \infty$) it holds. WDF für ML-Schätzer:

PDF for estimator converges Gauss PDF.

Likelihood \rightarrow Gauss and log-Likelihood \rightarrow parabola

$$\mathcal{L}(\theta) = \mathcal{L}(\hat{\theta}) \exp \left(-\frac{(\hat{\theta} - \theta)^2}{2V[\hat{\theta}]} \right) \quad \log \mathcal{L}(\theta) = \log \mathcal{L}(\hat{\theta}) - \frac{(\hat{\theta} - \theta)^2}{2V[\hat{\theta}]}$$

Bayesian Parameter Estimator

“Likelihood principle”: the results of the measurements is summarised by the likelihood function

$$L(\theta) = L(\vec{x}|\theta) = f_{\text{joint}}(\vec{x}|\theta)$$

Knowledge about parameter updated via Bayes theorem:

$$p(\theta|\vec{x}) = \frac{L(\vec{x}|\theta)\pi(\theta)}{\int L(\vec{x}|\theta')\pi(\theta') d\theta'}$$

Bayesian parameter estimate, by maximising the posterior probability $\hat{\theta}_{\text{Bayes}}$

How to choose prior $p(q)$? Often $\pi(\theta) = \text{constant}$ considered.

Then maximum likelihood and Bayesian estimators identical:

$$\hat{\theta}_{\text{Bayes}} = \hat{\theta}_{\text{ML}}$$

Example for Parameter Estimation

Frequentist: maximise likelihood

Bayesian: maximise posterior probability

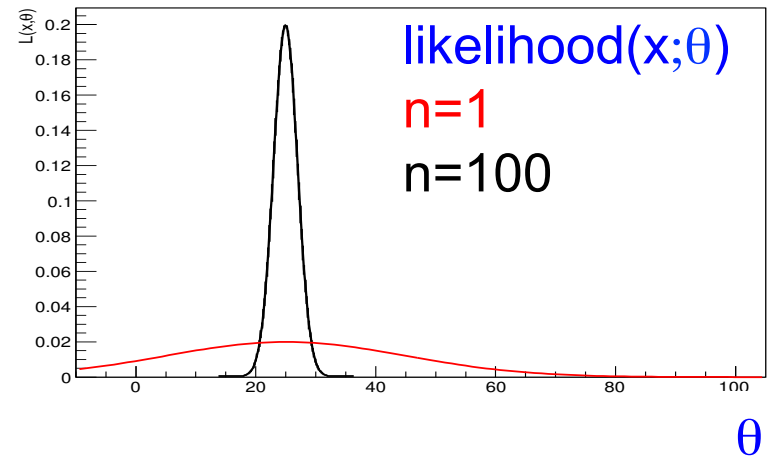
Estimation of mean value θ of Gaussian PDF

Resolution $\sigma = 20$.

Sample mean yields: $x = 25$

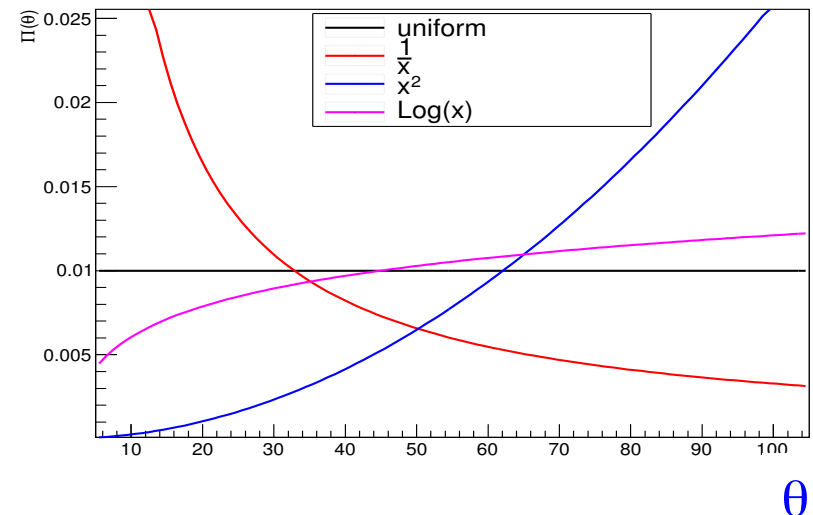
Consider two sample sizes: $n = 1$ (100)

→ Likelihood functions are
Gaussians with $\sigma/\sqrt{n} = 20$ (2)



Four different a-priori probabilities
for Bayesian estimate
normalised in range 5 to 105

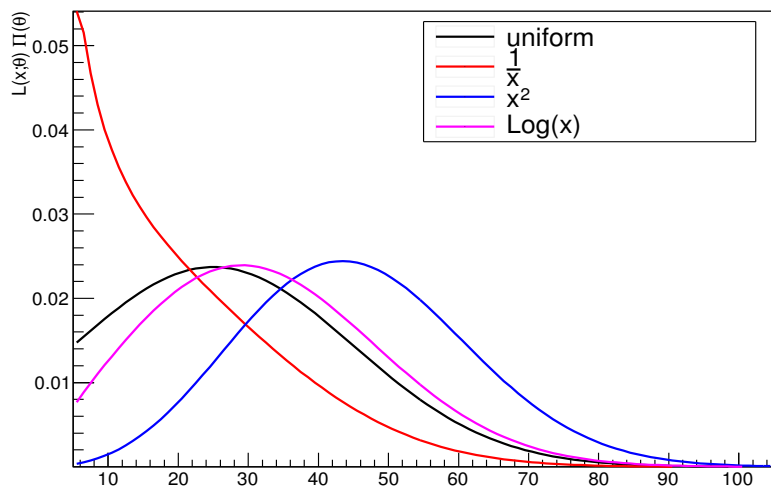
uniform, $1/x$, x^2 , $\ln(x)$



Parameter Estimation - Posterior Probabilities

Sample size $n = 1$

Large spread in posterior prob.

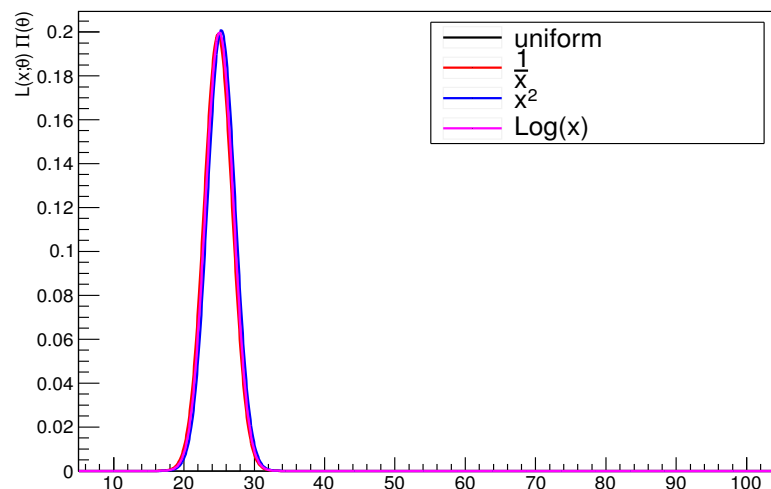


θ

Significant dependence of mode on a-priori probability

Large samples size $n = 100$

Small spread in posterior prob.



θ

Small dependence of mode on prior probability

For sample size $n \rightarrow \text{infinity}$ Bayesian and Frequentist results identical
Bayesian with uniform a-priority prob. and Frequentist numerical identical

Exception: in special situations e.g. close to a physical boundary

But interpretation is always different in both schools

Interpretation of CI: **Frequentist** and **Bayesian**

CI: Attempt for a probability statement connecting measurement with true value

- Frequentist:**
- objects to / can not make probability assignment to true values
 - construct a confidence interval CI $[a,b]$ at $xy\%$ CL from data in such a way that in a sequence of repeated identical measurements the fraction $xy\%$ of such intervals contains the true value
 - "the coverage probability of the interval is $XY\%$ "
 - no problems with "empty" intervals: $m_\nu^2 < -1 \text{ eV}^2$, $s < -0.3$ @95% CL

- Bayesian:**
- wants to make statement about probability of true value from single measurement
 - credibility interval / Bayesian confidence interval $[a,b]$ at $xy\%$ CL
 - probability / degree of belief that true values lies in $[a,b]$ is $xy\%$
 - coverage and outcome of not observed experiments not interesting
 - all information is in observed likelihood function \rightarrow likelihood principle
 - „empty“ intervals are meaningless in Bayesian interpretation but are avoided by an appropriate prior probability

Classical Frequentist Intervals

Neyman construction for equal tailed CI at CL = $1 - \alpha - \beta = 1 - \gamma$ $\alpha = \beta = \gamma/2$

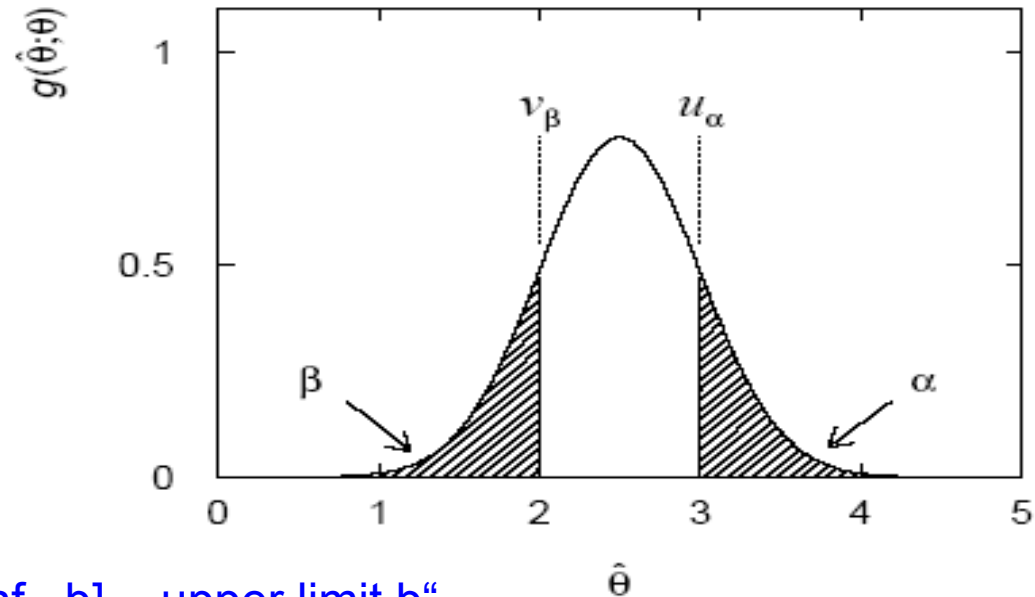
Consider: estimate $\hat{\theta}$ for parameter θ and measured value $\hat{\theta}_{\text{obs}}$.

Need PDF for estimate for all possible true values θ $g(\hat{\theta}; \theta)$.

Specify tail probabilities e.g. $\alpha = \beta = 0.025$ (0.16) and determine functions $u_{\alpha}(\theta)$ and $v_{\beta}(\theta)$ with:

$$\begin{aligned}\alpha &= P(\hat{\theta} \geq u_{\alpha}(\theta)) \\ &= \int_{u_{\alpha}(\theta)}^{\infty} g(\hat{\theta}; \theta) d\hat{\theta}\end{aligned}$$

$$\begin{aligned}\beta &= P(\hat{\theta} \leq v_{\beta}(\theta)) \\ &= \int_{-\infty}^{v_{\beta}(\theta)} g(\hat{\theta}; \theta) d\hat{\theta}\end{aligned}$$



for $\alpha = 0$, $u_{\alpha}(\theta) \rightarrow \inf \rightarrow]-\inf., b]$ „upper limit b“

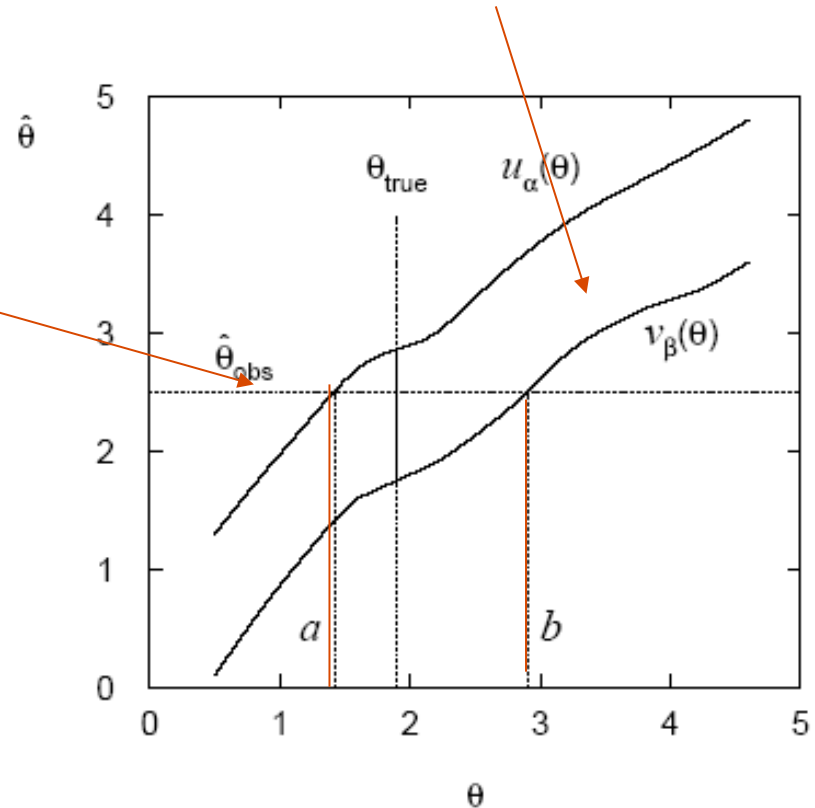
for $\beta = 0$, $v_{\beta}(\theta) \rightarrow -\inf \rightarrow [a, +\inf]$ „lower limit a“

Classical Frequentist Intervals

Region btw. $u_\alpha(\theta)$ and $v_\beta(\theta)$ is the confidence belt $P(l_\beta(\theta) \leq \hat{\theta} \leq u_\alpha(\theta)) = 1 - \alpha - \beta$

Boundaries of confidence interval given by intersect of observed value with confidence belt $\rightarrow [a, b]$

$$\begin{aligned} a(\hat{\theta}) &\equiv u_\alpha^{-1}(\hat{\theta}) \\ b(\hat{\theta}) &\equiv l_\beta^{-1}(\hat{\theta}). \end{aligned}$$



For all possible true values θ holds:

$$\begin{aligned} \hat{\theta} \geq u_\alpha(\theta) &\Leftrightarrow a(\hat{\theta}) \geq \theta & P(a(\hat{\theta}) \geq \theta) &= \alpha \\ \hat{\theta} \leq l_\beta(\theta) &\Leftrightarrow b(\hat{\theta}) \leq \theta, & P(b(\hat{\theta}) \leq \theta) &= \beta \end{aligned}$$

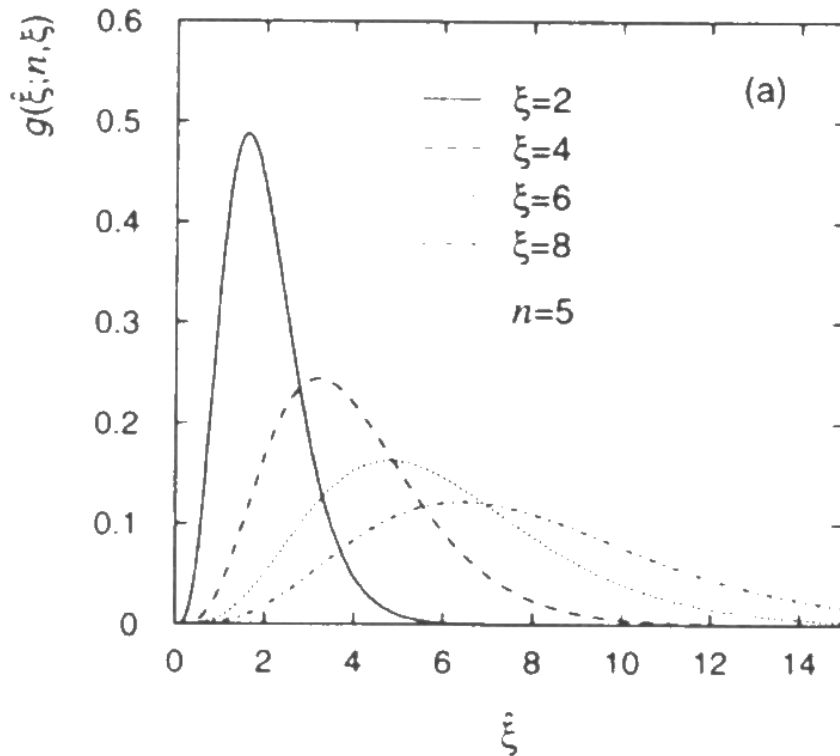
Correct coverage
by construction

$$P(a(\hat{\theta}) \leq \theta \leq b(\hat{\theta})) = 1 - \alpha - \beta.$$

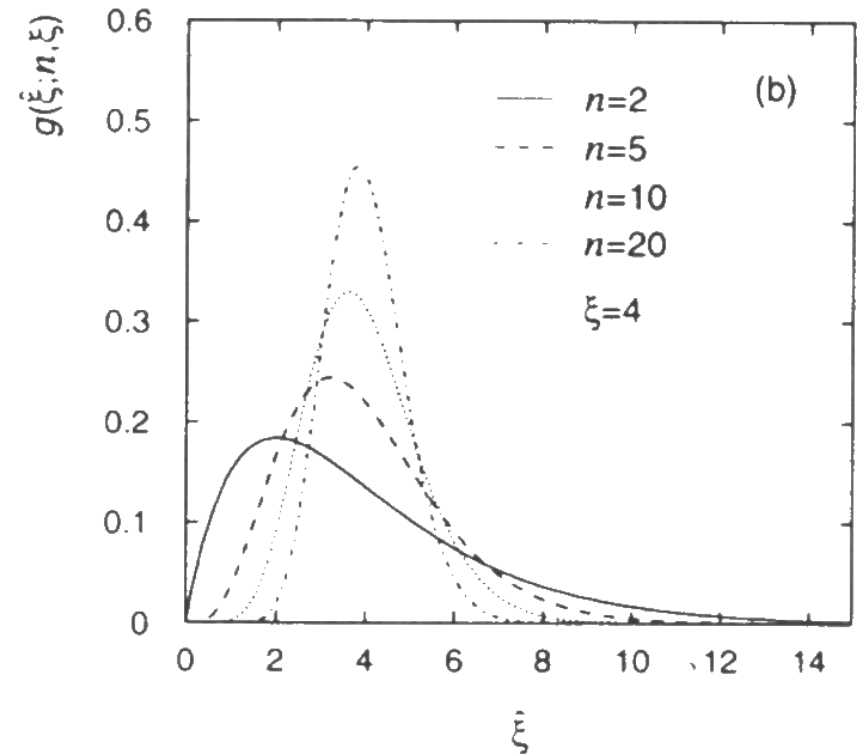
Construction of CI for Exponential PDF

ML-Schätzer Estimator = arithmetic mean of lifetimes

PDF for ML estimator is special case of gamma function



PDF for $N_{SP}=5$ various true lifetimes

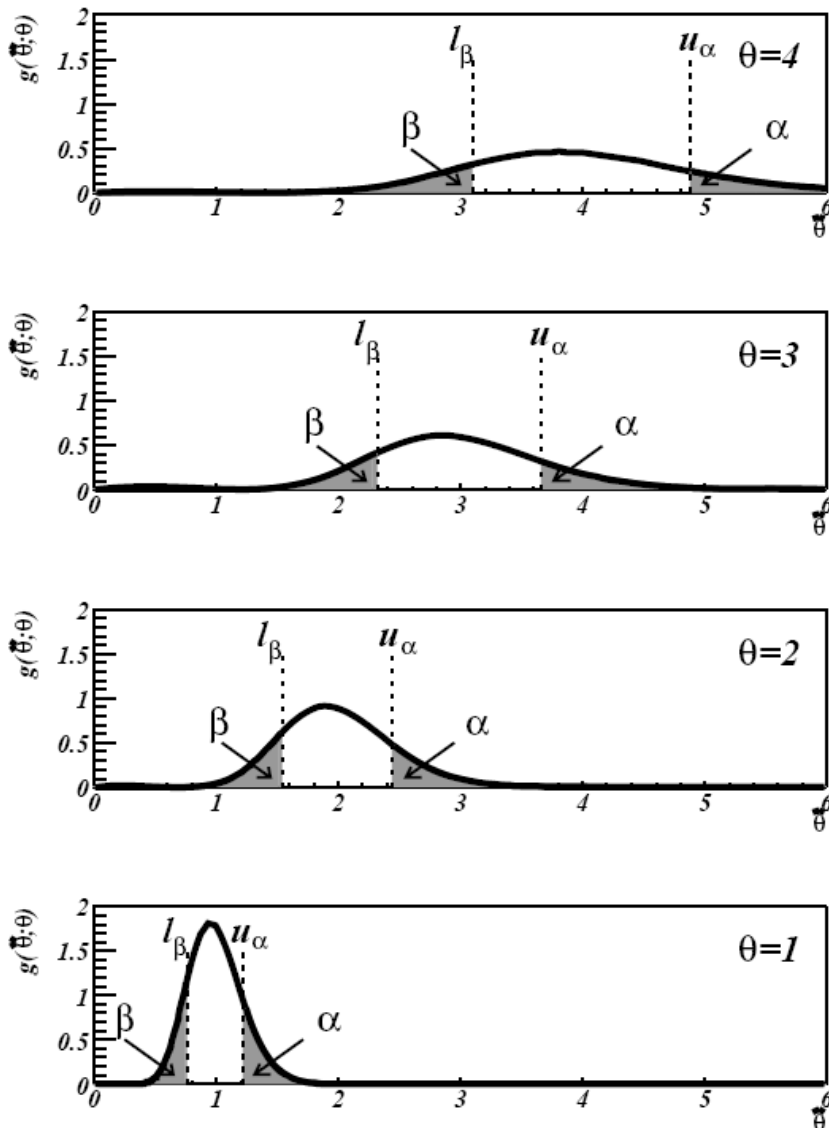


for true lifetime = 4, various N_{SP}

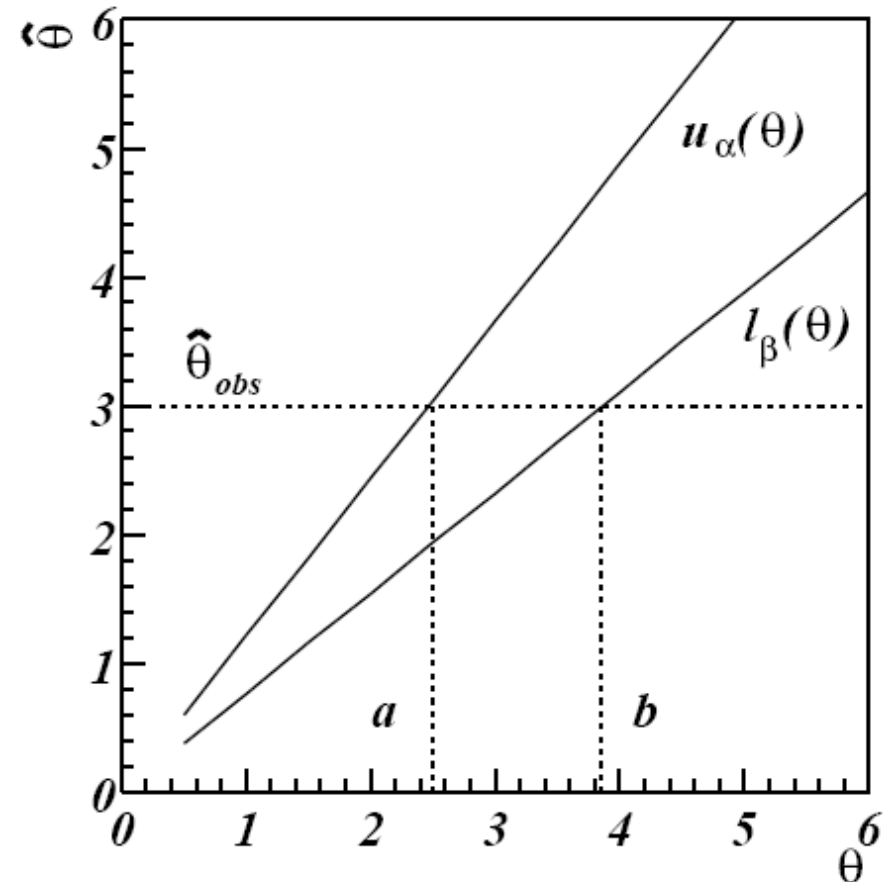
for $N_{SP} \rightarrow \infty$ PDF converges to Gaussian PDF due to Central Limit Theorem

Construction of CI for Exponential PDF (2)

PDF for ML-estimator for various true life times for sample size $N_{SP} = 20$



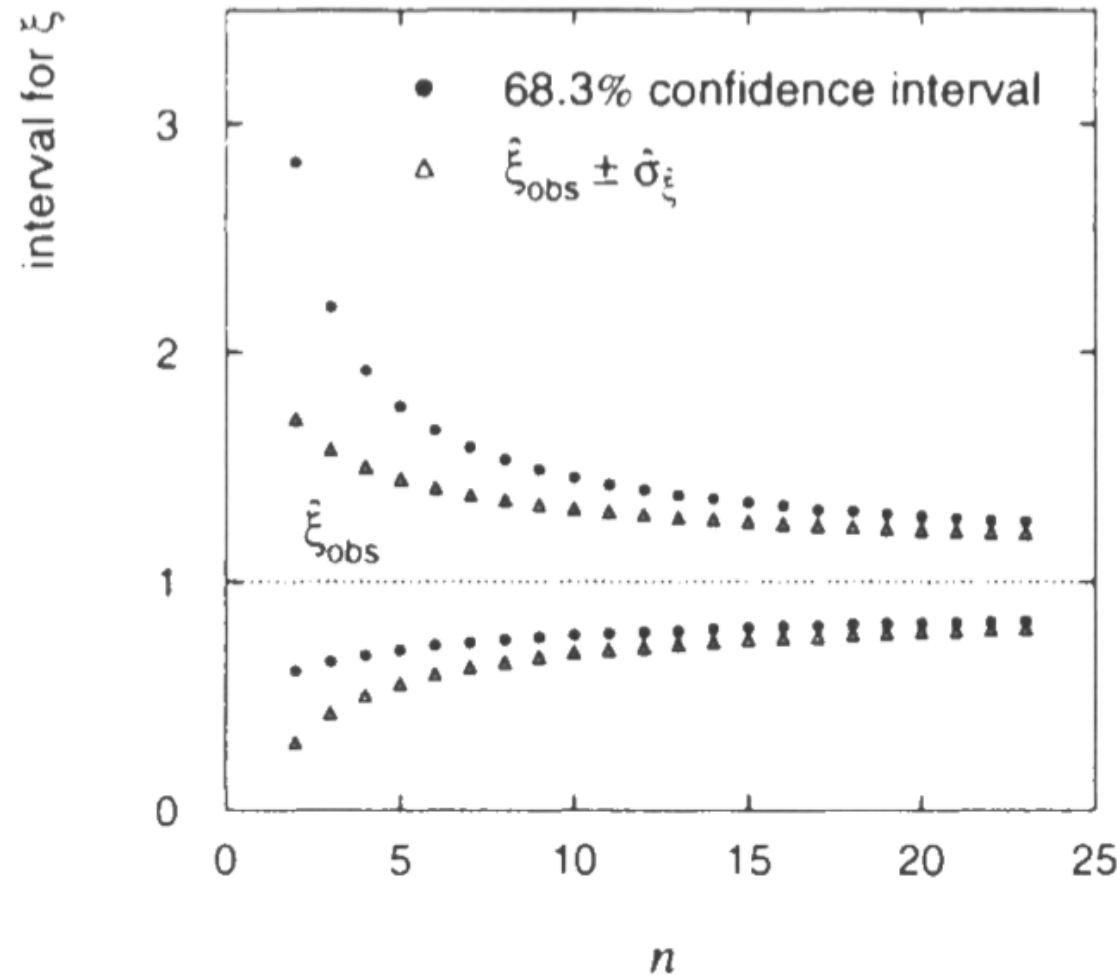
Confidence belt: u_α and l_β



Confidence interval $[a, b]$

Construction of CI for Exponential PDF (3)

Comparison of CI from estimator ± 1 standard deviation (triangles)
and from correct Nyman Construction (points)



for $n = N_{\text{SP}} \rightarrow \infty$ both CI get
identical as PDF for estimator
 \rightarrow Gauss-PDF f_{Gauss}

for finite/small $n = N_{\text{SP}}$

- correct Neyman CI longer
- coverage of naive CI
smaller than claimed CLI

Bayesian Credibility Interval

Result from experiment is posterior PDF for true parameter value θ

$$P(\theta; x_{SP}) = \text{const. } \mathcal{L}(x_{SP}; \theta) \pi(\theta)$$

Integrate posterior PDF to get CI $[a,b]$ at credibility $CL = 1 - \alpha - \beta$

$$\alpha = \int_{-\infty}^a P(\theta; x_{SP}) d\theta$$

lower limit $[a, \infty[$

$$\beta = \int_b^{\infty} P(\theta; x_{SP}) d\theta$$

upper limit $]-\infty, b]$

$$1 - \alpha - \beta = \int_a^b P(\theta; x_{SP}) d\theta$$

two sided CI $[a,b]$

Implement physical boundary via $\pi(\theta)$: $\pi(\theta) = 0$ in unphysical region

Repeatability of experiment and coverage is not of (main) interest for Bayesian